CANADIAN BOARD OF EXAMINERS FOR PROFESSIONAL SURVEYORS

SCHEDULE II / ITEM 1 GEODETIC POSITIONING

March 2009

<u>Marks</u>

Although programmable calculators may be used, candidates must show all formulae used, the substitution of values into them, and any intermediate values to 2 more significant figures than warranted by the answer. Otherwise, full marks may not be awarded even though the answer is numerically correct.

Note: This examination consists of 4 questions on 2 pages

<u>Q. No</u>	<u>Time: 3 hours</u>	Value	Earned
1	a) How is the International Terrestrial Reference System (ITRS) defined, realized and maintained. Enumerate the different observation techniques used and comment on the difference between <u>a</u> specific ITRF and <u>the</u> ITRS.	15	
	 b) What is the difference between ITRS and NAD83(CSRS) ? Explain the transformation between ITRF2000 and NAD83(CSRS) 3D Cartesian coordinates. 	11	
	c) If one looks back, an important realization of NAD was NAD27. Enumerate and explain 3 major differences in the definition and/or realization of NAD27 and NAD83(CSRS).	9	
2	 a) What are the characteristics, the applications and attainable accuracy of: Dual-frequency Real Time Kinematic (RTK)? Precise Point Positioning (PPP)? Single frequency Differential GPS (DGPS)? 	12	
	b) Comment on the disturbing potential of the troposphere and the ionosphere on the above mentioned methods i.e.: RTK, PPP, DGPS.	8	
3	a) Nowadays GPS is widely used for positioning purposes. The height obtained from GPS is basically a height above the ellipsoid. Would it not therefore be more suitable to drop the geoid as a reference surface completely and to switch to the ellipsoid as vertical datum using ellipsoidal heights only? Argue.	5	

