CANADIAN BOARD OF EXAMINERS FOR PROFESSIONAL SURVEYORS

C6 - GEODETIC POSITIONING

October 2017

ote:	This examination	consists of 5	questions on	2 pages.
------	------------------	---------------	--------------	----------

Marks

S(CSRS): . "3478 . "5612 nce between NAD83 e of measurements S. (just giving a	10	
nce between NAD83 e of measurements (i. (just giving a		
e of measurements i. (just giving a		
rill not be accepted).	5	
c) Explain (without any actual numerical calculation) how you obtain UTM coordinates for Marker A and the grid bearing (in UTM) from A to B.		
d) The marker <i>C</i> is located 300.000 m to the south and 200.000 m to the east of marker <i>A</i> . Calculate latitude and longitude of marker <i>C</i> . You may assume that the given values are distances on the ellipsoid. (Just giving a numerical result without commenting on how you got it will not be sufficient).		
You are responsible for a local survey in a rural area. The network consists of 50 points distributed homogeneously over an area of 10 km x 10 km. Your task is to determine the UTM coordinates of all 50 points with respect to NAD83 (CSRS). An accuracy of 2 cm is required. At your disposition are 5 dual frequency receivers capable of RTK.		
a) Explain what RTK stands for and how it works. What type of GPS observations are used? Which accuracy can be achieved? Why are dual frequency measurements mandatory?		
b) What is a PDOP and how is it obtained? What is its use?		
c) Explain your strategy for solving this task and meeting the required accuracy in terms of number of reference stations used, occupation plan with rovers, ties to NAD83 (CSRS), total duration in days.		
ordinates of all M stands for and	5	
	you obtain UTM from A to B. 2000 m to the east of You may assume that g a numerical result nt). twork consists of 50 20 km. Your task is to to NAD83 (CSRS). hal frequency be of GPS Why are dual de required accuracy plan with rovers, ordinates of all M stands for and	you obtain UTM from A to B. 000 m to the east of You may assume that g a numerical result nt). twork consists of 50 0 km. Your task is to to NAD83 (CSRS). Ital frequency be of GPS Why are dual 10 5 re required accuracy plan with rovers, ordinates of all M stands for and 5

	Total Marks:	100	
5.	What is the name of the official new vertical datum in Canada? How has it been realized and how is it maintained? What are the advantages of changing to this new approach? Do you see any disadvantages?	10	
7.	be determined by VLBI <i>only</i> and not by GPS? Justify. b) Explain what polar motion accounts for.	5	
4.	a) VLBI is a geodetic space technique that contributes to the determination of the Earth Rotation parameters. Explain how VLBI works. Which EOPs can		
	The International Earth Rotation and Reference Systems Service (IERS) publishes the following Earth orientation parameters: i) polar motion (x,y) , ii) universal time (UT1 – UTC, UT1 – TAI), iii) Celestial pole offsets $(\Delta \psi, \Delta \varepsilon)$.		
	d) Define orthometric heights. How are they obtained from geopotential numbers?	4	
	c) How do you convert geopotential numbers to dynamic heights?		
3.	b) Which <u>type</u> of measurements do you need to determine geopotential numbers? Explain <i>with formulas</i> how they are obtained.		
	a) Define geopotential numbers and give their SI-units.	3	
	Quotation from a publication by David B. Zilkoski (NOAA): There are several different height systems used by the surveying and mapping community. Two of these height systems are relevant to the International Great Lakes Datum of 1985 (IGLD 85): orthometric heights and dynamic heights. Geopotential numbers relate these two systems to each other.		