

CANADIAN BOARD OF EXAMINERS FOR PROFESSIONAL SURVEYORS

C-2 LEAST SQUARES ESTIMATION & DATA ANALYSIS

October 2010

Note: This examination consists of 8 questions on 3 pages.

Although programmable calculators may be used, candidates must show all formulae used, the substitution of values into them, and any intermediate values to 2 more significant figures than warranted for the answer. Otherwise, full marks may not be awarded even though the answer is numerically correct.

Marks

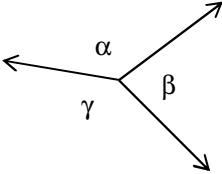
Q. No

Time: 3 hours

Value Earned

1.	<p>Define and explain briefly the following terms:</p> <ul style="list-style-type: none"> a) Precision b) Accuracy c) Correlation coefficient d) Redundancy of a linear system e) Type II errors in statistical testing 	10	
2.	<p>Given the leveling network below where A and B are known points, h_1 and h_2 are two height difference measurements with standard deviation of σ_1 and σ_2, respectively and $\sigma_1 = 2 \sigma_2$. Determine the value of σ_1 and σ_2 so that the standard deviation of the height solution at P using least squares adjustment is equal to 2cm.</p> <div align="center" data-bbox="505 1087 1015 1234"> </div>	10	
3.	<p>Given the following mathematical model</p> $f(\ell, x) = 0 \quad C_\ell \quad C_x$ <p>where f is the vector of mathematical models, x is the vector of unknown parameters and C_x is its variance matrix, ℓ is the vector of observations and C_ℓ is its variance matrix.</p> <ul style="list-style-type: none"> a) Linearize the mathematical model. b) Formulate the variation function. c) Derive the least squares normal equation. 	15	

4.	<p>Given the variance-covariance matrix of the horizontal coordinates (x, y) of a survey station, determine the semi-major, semi-minor axis and the orientation of the standard error ellipse associated with this station.</p> $C_x = \begin{bmatrix} 0.000532 & 0.000602 \\ 0.000602 & 0.000838 \end{bmatrix} m^2$	10													
5.	<p>Given the variance-covariance matrix of the measurement vector $l = \begin{bmatrix} l_1 \\ l_2 \end{bmatrix}$:</p> $C_l = \begin{bmatrix} \frac{2}{3} & \frac{1}{3} \\ \frac{1}{3} & \frac{2}{3} \end{bmatrix}$ <p>and two functions of l: $x = l_1 + l_2$ and $y = 3l_1$, determine C_{xy}, C_{xl}, C_{yl}</p>	10													
6.	<p>Given the sample unit variance obtained from the adjustment of a geodetic network $\hat{\sigma}_0^2 = 0.55 \text{ cm}^2$ with a degree of freedom $\nu = 3$ and the a-priori standard deviation $\sigma_0 = 0.44 \text{ cm}$, conduct a statistic test to decide if the adjustment result is acceptable with a significance level of $\alpha = 5\%$. Provide the major test steps and explain the conclusion.</p> <p>The critical values that might be required in the testing are provided in the following table:</p> <table border="1" data-bbox="391 1163 1154 1341"> <tr> <td>α</td> <td>0.001</td> <td>0.01</td> <td>0.025</td> <td>0.05</td> <td>0.10</td> </tr> <tr> <td>$\chi_{\alpha, \nu=3}^2$</td> <td>16.26</td> <td>11.34</td> <td>9.35</td> <td>7.82</td> <td>6.25</td> </tr> </table> <p>where $\chi_{\alpha, \nu=3}^2$ is determined by the equation $\alpha = \int_{\chi_{\alpha, \nu=3}^2}^{\infty} \chi^2(x) dx$.</p>	α	0.001	0.01	0.025	0.05	0.10	$\chi_{\alpha, \nu=3}^2$	16.26	11.34	9.35	7.82	6.25	10	
α	0.001	0.01	0.025	0.05	0.10										
$\chi_{\alpha, \nu=3}^2$	16.26	11.34	9.35	7.82	6.25										

7.	<p>A baseline of calibrated length (μ) 200.0m is measured 5 times. Each measurement is independent and made with the same precision. The sample mean (\bar{x}) and sample standard deviation (s) are calculated from the measurements:</p> $\bar{x} = 200.5m \qquad s = 0.05m$ <p>Test at the 95% level of confidence if the measured distance is significantly different from the calibrated distance.</p> <p>The critical value that might be required in the testing is provided in the following table:</p> <table border="1" data-bbox="279 541 1247 940"> <thead> <tr> <th></th> <th colspan="4">t_{α}</th> </tr> <tr> <th>Degree of freedom</th> <th>$t_{0.90}$</th> <th>$t_{0.95}$</th> <th>$t_{0.975}$</th> <th>$t_{0.99}$</th> </tr> </thead> <tbody> <tr> <td>1</td> <td>3.08</td> <td>6.31</td> <td>12.7</td> <td>31.8</td> </tr> <tr> <td>2</td> <td>1.89</td> <td>2.92</td> <td>4.30</td> <td>6.96</td> </tr> <tr> <td>3</td> <td>1.64</td> <td>2.35</td> <td>3.18</td> <td>4.54</td> </tr> <tr> <td>4</td> <td>1.53</td> <td>2.13</td> <td>2.78</td> <td>3.75</td> </tr> <tr> <td>5</td> <td>1.48</td> <td>2.01</td> <td>2.57</td> <td>3.36</td> </tr> </tbody> </table>		t_{α}				Degree of freedom	$t_{0.90}$	$t_{0.95}$	$t_{0.975}$	$t_{0.99}$	1	3.08	6.31	12.7	31.8	2	1.89	2.92	4.30	6.96	3	1.64	2.35	3.18	4.54	4	1.53	2.13	2.78	3.75	5	1.48	2.01	2.57	3.36	10	
	t_{α}																																					
Degree of freedom	$t_{0.90}$	$t_{0.95}$	$t_{0.975}$	$t_{0.99}$																																		
1	3.08	6.31	12.7	31.8																																		
2	1.89	2.92	4.30	6.96																																		
3	1.64	2.35	3.18	4.54																																		
4	1.53	2.13	2.78	3.75																																		
5	1.48	2.01	2.57	3.36																																		
8.	<p>Given the angle measurements at a station along with their standard deviations:</p> <table border="1" data-bbox="370 1071 1143 1234"> <thead> <tr> <th>Angle</th> <th>Measurement</th> <th>Standard Deviation</th> </tr> </thead> <tbody> <tr> <td>α</td> <td>134°38'56"</td> <td>6.7"</td> </tr> <tr> <td>β</td> <td>83°17'35"</td> <td>9.9"</td> </tr> <tr> <td>γ</td> <td>142°03'14"</td> <td>4.3"</td> </tr> </tbody> </table>  <p>Perform least squares adjustment to the problem using</p> <ol style="list-style-type: none"> Conditional equations (conditional adjustment) Observation equations (parametric adjustment) 	Angle	Measurement	Standard Deviation	α	134°38'56"	6.7"	β	83°17'35"	9.9"	γ	142°03'14"	4.3"	25																								
Angle	Measurement	Standard Deviation																																				
α	134°38'56"	6.7"																																				
β	83°17'35"	9.9"																																				
γ	142°03'14"	4.3"																																				
Total Marks:		100																																				