

**CANADIAN BOARD OF EXAMINERS FOR PROFESSIONAL SURVEYORS  
ATLANTIC PROVINCES BOARD OF EXAMINERS FOR LAND SURVEYORS**

**SCHEDULE I / ITEM 2**

**March 1007**

**LEAST SQUARES ESTIMATION AND DATA ANALYSIS**

**Note: This examination consists of 8 questions on 3 pages.**

**Marks**

**Q. No**

**Time: 3 hours**

**Value   Earned**

1	<p>Given the following mathematical models</p> $\mathbf{f}_1(\ell_1, \mathbf{x}_1) = 0 \quad \mathbf{C}_{\ell_1} \quad \mathbf{C}_{x_1}$ $\mathbf{f}_2(\ell_2, \mathbf{x}_1, \mathbf{x}_2) = 0 \quad \mathbf{C}_{\ell_2} \quad \mathbf{C}_{x_2}$ <p>where <math>\mathbf{f}_1</math> and <math>\mathbf{f}_2</math> are vectors of mathematical models, <math>\mathbf{x}_1</math> and <math>\mathbf{x}_2</math> are vectors of unknown parameters, <math>\ell_1</math> and <math>\ell_2</math> are vectors of observations, <math>\mathbf{C}_{\ell_1}</math>, <math>\mathbf{C}_{\ell_2}</math>, <math>\mathbf{C}_{x_1}</math> and <math>\mathbf{C}_{x_2}</math> are covariance matrices.</p> <p>a) Linearize the mathematical models b) Formulate the variation function</p>	10	
2	<p>Given n independent measurements of a single quantity: <math>\ell_1, \ell_2, \dots, \ell_n</math> and their corresponding standard deviations: <math>\sigma_1, \sigma_2, \dots, \sigma_n</math>, derive the expression for the variance of the mean value using the Law of Propagation of Variances.</p>	10	
3	<p>Given the following variance-covariance matrix from a least squares adjustment for the coordinates of point A and B,</p> $\mathbf{C}_x = \begin{bmatrix} 10 & 5 & 2 & 1 \\ 5 & 10 & 1 & 1 \\ 2 & 1 & 5 & 2 \\ 1 & 1 & 2 & 5 \end{bmatrix} \text{ m}^2 \quad \text{where } \mathbf{x} = [x_A \quad y_A \quad x_B \quad y_B]^T.$ <p>a) Compute the correlation coefficient between <math>x_A</math> and <math>y_B</math>. b) Compute the correlation coefficient between <math>y_A</math> and <math>x_B</math>. c) Compute the variance-covariance matrix for the coordinate differences <math>\Delta x = x_B - x_A</math> and <math>\Delta y = y_B - y_A</math>.</p>	10	

4	<p>Given the covariance matrix of the horizontal coordinates (x, y) of a survey station, determine the semi-major, semi-minor axis and the orientation of the standard error ellipse associated with this station.</p> $C_x = \begin{bmatrix} 0.0484 & 0.0246 \\ 0.0246 & 0.0196 \end{bmatrix} m^2$	10																																			
5	<p>Define or explain the following terms:</p> <ol style="list-style-type: none"> <li>1) Precision</li> <li>2) Accuracy</li> <li>3) Statistical independence</li> <li>4) Type I error</li> <li>5) Type II error</li> <li>6) Expectation</li> <li>7) Degree of freedom of a linear system</li> </ol>	15																																			
6	<p>Given 20 independent measurements of a distance made with the same standard deviation of 0.033m and the calculated mean value <math>\mu = 37.615m</math>, construct a 95% confidence interval for the population mean.</p> <p style="text-align: center;"><b>Percentiles of Standard Normal Distribution</b></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <tr> <td><math>\alpha</math></td> <td>0.002</td> <td>0.003</td> <td>0.004</td> <td>0.005</td> <td>0.01</td> <td>0.025</td> <td>0.05</td> </tr> <tr> <td><math>K_\alpha</math></td> <td>2.88</td> <td>2.75</td> <td>2.65</td> <td>2.58</td> <td>2.33</td> <td>1.96</td> <td>1.64</td> </tr> </table> <p style="text-align: center;">where <math>K_\alpha</math> is determined by the equation <math>\alpha = \int_{K_\alpha}^{\infty} \frac{1}{\sqrt{2\pi}} e^{-x^2/2} dx</math>.</p>	$\alpha$	0.002	0.003	0.004	0.005	0.01	0.025	0.05	$K_\alpha$	2.88	2.75	2.65	2.58	2.33	1.96	1.64	10																			
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7	<p>A baseline of calibrated length (<math>\mu</math>) 1153.00m is measured 5 times independently with the same precision. The sample mean (<math>\bar{x}</math>) and sample standard deviation (s) are calculated from the measurements:</p> <p style="text-align: center;"><math>\bar{x} = 1153.39m</math>                      <math>s = 0.06m</math></p> <p>Test at a 90% confidence level (<math>\alpha</math>) if the measured distance is significantly different from the calibrated distance.</p> <p style="text-align: center;"><b>Percentiles of t distribution</b></p> <table border="1" style="margin-left: auto; margin-right: auto;"> <thead> <tr> <th rowspan="2">Degree of freedom</th> <th colspan="4"><math>t_\alpha</math></th> </tr> <tr> <th><math>t_{0.90}</math></th> <th><math>t_{0.95}</math></th> <th><math>t_{0.975}</math></th> <th><math>t_{0.99}</math></th> </tr> </thead> <tbody> <tr> <td>1</td> <td>3.08</td> <td>6.31</td> <td>12.7</td> <td>31.8</td> </tr> <tr> <td>2</td> <td>1.89</td> <td>2.92</td> <td>4.30</td> <td>6.96</td> </tr> <tr> <td>3</td> <td>1.64</td> <td>2.35</td> <td>3.18</td> <td>4.54</td> </tr> <tr> <td>4</td> <td>1.53</td> <td>2.13</td> <td>2.78</td> <td>3.75</td> </tr> <tr> <td>5</td> <td>1.48</td> <td>2.01</td> <td>2.57</td> <td>3.36</td> </tr> </tbody> </table>	Degree of freedom	$t_\alpha$				$t_{0.90}$	$t_{0.95}$	$t_{0.975}$	$t_{0.99}$	1	3.08	6.31	12.7	31.8	2	1.89	2.92	4.30	6.96	3	1.64	2.35	3.18	4.54	4	1.53	2.13	2.78	3.75	5	1.48	2.01	2.57	3.36	10	
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Given in the following is a diagram of a leveling network to be adjusted.

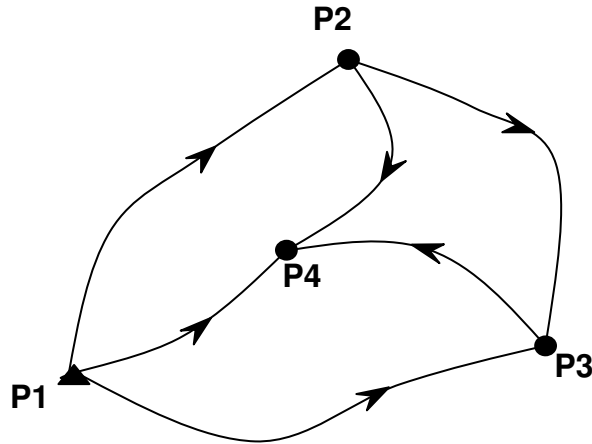


Table 1 contains all of the height difference measurements  $\Delta h_{ij}$  necessary to carry out the adjustment. Assume that all observations have the same standard deviation  $\sigma_{\Delta h_{ij}} = 0.04\text{m}$ . P1 is a fixed point with known elevations of  $H_1 = 101.00\text{m}$ . Perform least squares adjustment on the leveling network to compute:

8

25

- the adjusted elevations of point P2, P3 and P4 and their variance-covariance matrix;
- the observation residuals;
- the adjusted height differences; and
- the a-posteriori variance factor  $\hat{\sigma}_0$ .

**Table 1**

No.	i	j	$\Delta h_{ij}$ (unit: metre)
1	P1	P3	6.15
2	P1	P4	12.54
3	P3	P4	6.46
4	P1	P2	1.11
5	P2	P4	11.55
6	P2	P3	5.10

**Total Marks:**

100